

Wisdom Education Academy

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Introduction

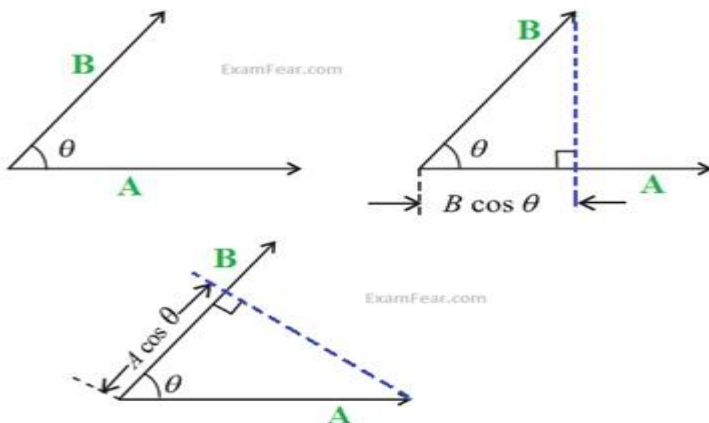
We use the words work, energy and power in our day-to-day life often.



However, their meaning differ from the meaning we get from scientific definitions.

Scalar product

- The scalar product or dot product of any two vectors A and B , denoted as $A \cdot B$ (Read A dot B) is defined as $AB \cos \theta$, where θ is the angle between the two vectors.
- A , B and $\cos \theta$ are scalars, the dot product of A and B is a scalar quantity. Both vectors, A and B , have a direction but their scalar product does not have a direction.
- $B \cos \theta$ is the product of the magnitude of B and the component of B along A . Alternatively, it is the product of the magnitude of A and the component of A along B .



- $B \cdot A = A \cdot B$, i.e. Scalar product is commutative.
- $(B + C) \cdot A = A \cdot B + A \cdot C$, i.e. Scalar product is distributive.
- Further, $\lambda A \cdot B = \lambda (A \cdot B)$ where λ is a real number.

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k} \text{ \& \; } \vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k} \text{ then the scalar product}$$
$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

Notions of Work and Kinetic Energy

- The work-energy theorem states that the change in kinetic energy of a particle is equal to the work done on it by the net force.
- $K_f - K_i = W$
- We know the equation in 3D : $v^2 - u^2 = 2a.d$ (where u-initial velocity, v-final velocity, a-acceleration, d-displacement)
now multiplying the equation by $m/2$ we have, $\frac{1}{2} mv^2 - \frac{1}{2} mu^2 = ma.d = F.d$ (Since $ma = F$)

Work

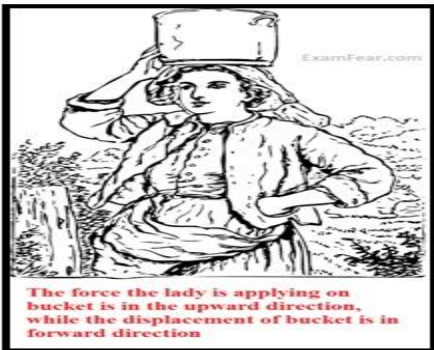
The work done by the force is defined to be the product of component of the force in the direction of the displacement and the magnitude of this displacement. $W = \mathbf{F} \cdot \mathbf{d}$.

No work is done if:

- The displacement is zero



- The force is zero.
- The force and displacement are mutually perpendicular.



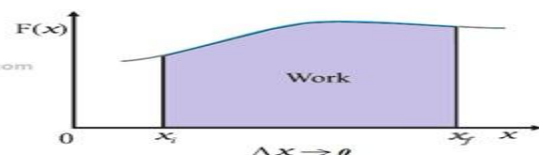
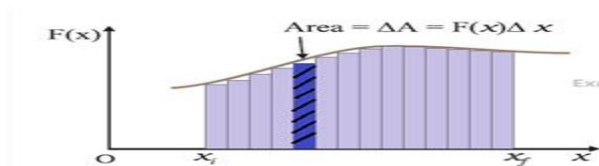
Work done by a variable force

- The variable force is more commonly encountered than the constant force.
- If the displacement Δx is small, we can take the force $F(x)$ as approximately constant and the work done is then $\Delta W = F(x) \Delta x$

For total work, we add all work done along small displacements.

$$W = \lim_{\Delta x \rightarrow 0} \sum_{x_i}^{x_f} F(x) \Delta x$$

$$W = \int_{x_i}^{x_f} F(x) dx$$



Example: A force $F = 3x^2$ start acting on a particle which is initially at rest. Find the work done by the force during the displacement of the particle from $x = 0\text{m}$ to $x = 2\text{m}$.

Solution: We know that $W = \int_{x_i}^{x_f} F(x)dx$,

$$W = \int_0^2 3x^2 \cdot dx$$

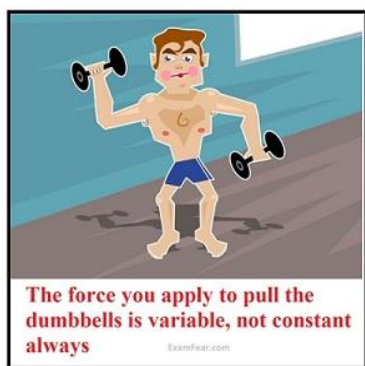
$$W = \frac{3(2)^3}{3} - \frac{3(0)^3}{3} = 8 \text{ N-m}$$

Kinetic energy

- The kinetic energy of an object is a measure of the work an object can do by the virtue of its motion.
- If an object of mass m has velocity v , its kinetic energy K is
- Kinetic energy is a scalar quantity.

The Work-Energy Theorem for a Variable Force

- $\frac{dK}{dt} = \frac{d}{dt} \left(\frac{1}{2} m v^2 \right) = \frac{dK}{dt} = m \left(\frac{dv}{dt} \right) v$
- Since dv/dt is acceleration, $m \cdot a$ becomes force $\frac{dK}{dt} = Fv = F \frac{dx}{dt}$
- $dK = F dx$, integrating this equation we get $K_f - K_i = W$

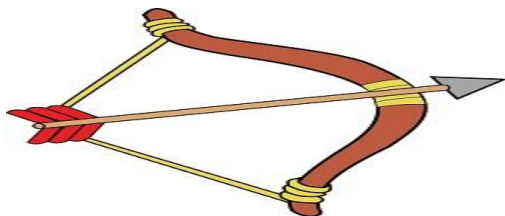


Example: A body of mass 0.5 kg travels in a straight line with velocity $v = a x^{3/2}$ where $a = 5 \text{ m}^{-1/2} \text{ s}^{-1}$. What is the work done by the net force during its displacement from $x = 0$ to $x = 2 \text{ m}$

Solution: We know that $W = K_f - K_i$, now we can put value of $x=0$ in the equation $v = a x^{3/2}$ to find initial velocity, $v_i=0$, $K_i=0$,
Similarly find v_f by putting $x=2$, and $K_f = \frac{1}{2} m v^2$.

Potential energy

- Potential energy is the 'stored energy' by virtue of the position or configuration of a body.



- Physically, the notion of potential energy is applicable only to the class of forces where work done against the force gets 'stored up' as energy.
- Mathematically, the potential energy $V(x)$ is defined, if the force $F(x)$ can be written

$$F(x) = - \frac{dV}{dx} .$$

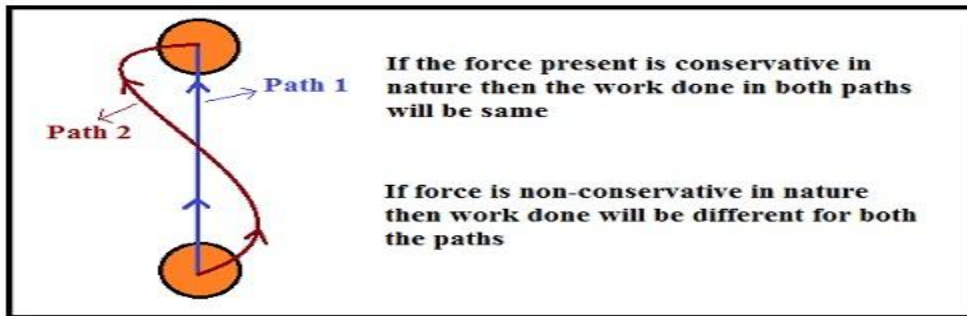
$$\int_{x_i}^{x_f} F(x) = V_i - V_f$$

as

- This relation is valid only for Conservative Forces

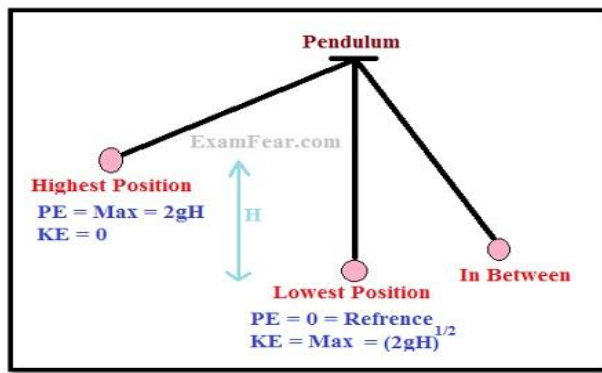
Conservative & Non-Conservative Forces

- Conservative forces are those for which work done depends only on initial and final points.
Example- Gravitational force, Electrostatic force.
- Non-Conservative forces are those where the work done or the kinetic energy did depend on other factors such as the velocity or the particular path taken by the object.
Example- Frictional force.



The Conservation of Mechanical Energy

- Mechanical Energy is the energy associated with the motion and position of an object.
- The quantity $K + V(x)$, is called the total mechanical energy of the system.
- For a conservative force, $\Delta K = \Delta W = F(x) \Delta x$
Also, $- \Delta V(x) = F(x) \Delta x$
- This employs $\Delta(K+V) = 0$ for a conservative force.
- Individually the kinetic energy K and the potential energy $V(x)$ may vary from point to point, but the sum is a constant.
- Conservative Force:
- A force $F(x)$ is conservative if it can be derived from a scalar quantity $V(x)$ by the relation : $F(x) = - dv/dx$
- The work done by the conservative force depends only on the end points.
- A third definition states that the work done by this force in a closed path is zero.
- The total mechanical energy of a system is conserved if the forces, doing work on it, are conservative.

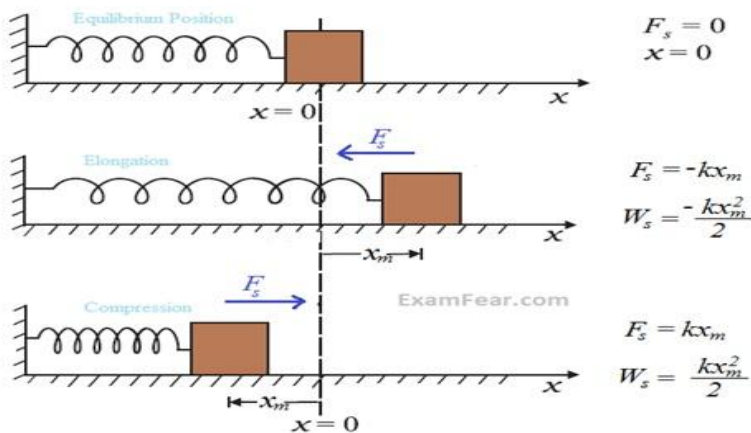


Potential energy of spring

- The spring force is an example of a variable force, which is conservative.
- In an ideal spring, $F_s = -kx$, this force law for the spring is called Hooke's law.
- The constant k is called the spring constant. Its unit is N m^{-1} .
- The spring is said to be stiff if k is large and soft if k is small.

$$W_s = - \int_{x_i}^{x_f} kx \, dx$$

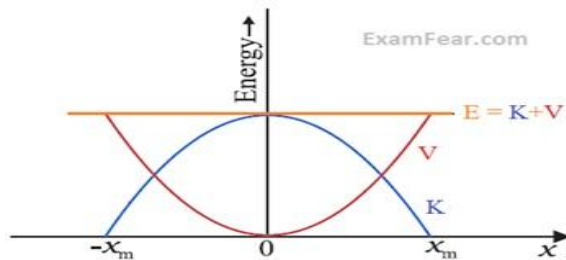
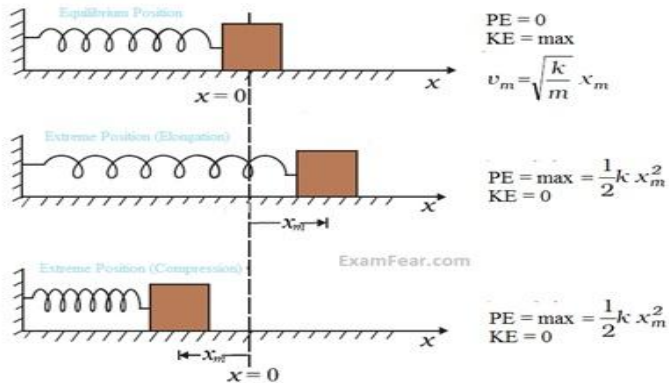
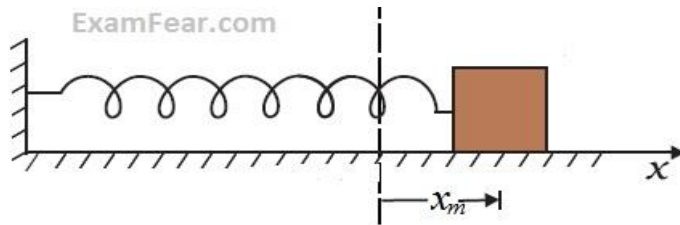
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- Spring force is position dependent as first stated by Hooke, ($F_s = -kx$)
- Work done by spring force only depends on the initial and final positions. Thus, the spring force is a conservative force.
- We define the potential energy $V(x)$ of the spring to be zero when block and spring system is in the equilibrium position.
- For an extension (or compression) x , $V(x) = kx^2/2$

If the block of mass m is extended to x_m and released from rest, then its total mechanical energy at any arbitrary point x (where x lies between $-x_m$ and $+x_m$) will be given by:

$$\frac{1}{2} kx_m^2 = \frac{1}{2} kx^2 + \frac{1}{2} mv^2$$



Example: A car of mass M travelling with speed v , collides with a spring, having spring constant k . The car comes to rest (momentarily) when spring is compressed to a distance of x_m . Find x_m .

Solution: Work done on car $= K_f - K_i = 0 - \frac{mv^2}{2} = -\frac{mv^2}{2}$

Work done by spring, $W_s = -\int_{x_i}^{x_f} kx \, dx = -\int_0^{x_m} kx \, dx = -\frac{kx_m^2}{2}$

Now work done by spring equals work done on car $\Rightarrow -\frac{mv^2}{2} = -\frac{kx_m^2}{2}$

$$x_m = \sqrt{\frac{m}{k}} v$$

Various forms of energy

Heat: The work done by friction is not 'lost', but is transferred as heat energy

Chemical Energy:

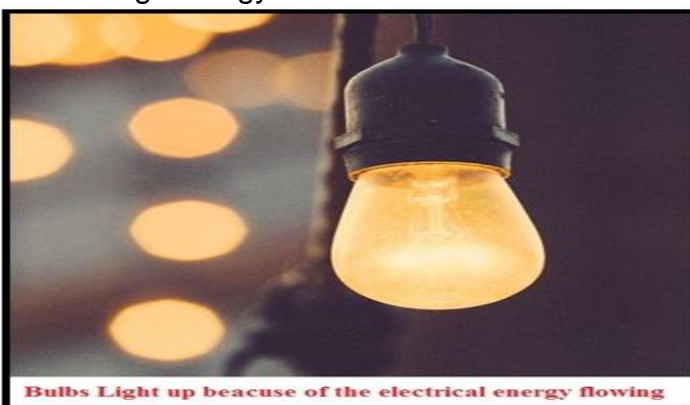
- Chemical energy arises from the fact that the molecules participating in the chemical reaction have different binding energies.
- If the total energy of the reactants is more than the products of the reaction, heat is released and the reaction is said to be an exothermic reaction.

Example- When you freeze water you remove energy from water to lower its temperature and its phase is changed to ice, so it is a exothermic process

- If the reverse is true, heat is absorbed and the reaction is endothermic.
Example- While melting the ice you provide energy to the ice to increase its temperature and change its phase to water, so it is a endothermic process.



Electrical Energy: The flow of electrical current causes bulbs to glow, fans to rotate and bells to ring. Energy is associated with an electric current.



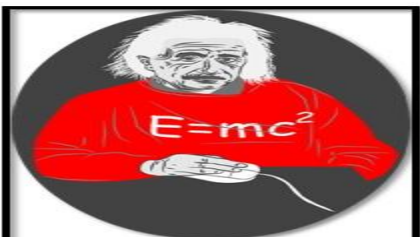
Nuclear Energy:

- The energy released from the nuclear reactions, either fission or fusion, is called as nuclear energy.
- Nuclear fusion and fission are manifestations of the equivalence of mass and energy.
- In fusion light atom nuclei like Hydrogen fuse to form a bigger nucleus whose mass is less than the sum of the masses of the reactants.
- In fission, a heavy nucleus like uranium $^{235}\text{U}_{92}$, is split by a neutron into lighter nuclei. Once again the final mass is less than the initial mass and the mass difference translates into energy.



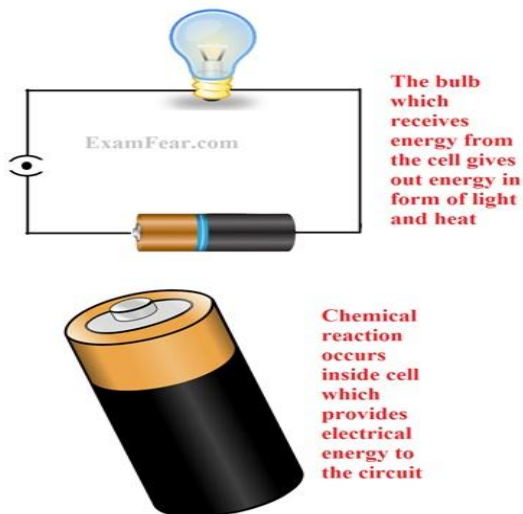
The Equivalence of Mass and Energy

- Physicists believed that in every physical and chemical process, the mass of an isolated system is conserved till Albert Einstein show the relation , $E = m c^2$ where c , the speed of light in vacuum is approximately $3 \times 10^8 \text{ m s}^{-1}$.
- This equation showed that mass and energy are equivalent and are related by $E = m c^2$.
- If there is a difference between the sum of reactants and products that difference, Δm , is called mass defect.
- In case of chemical reactions the mass defect is very small and can be neglected, but in the case of nuclear reactions this becomes significant.



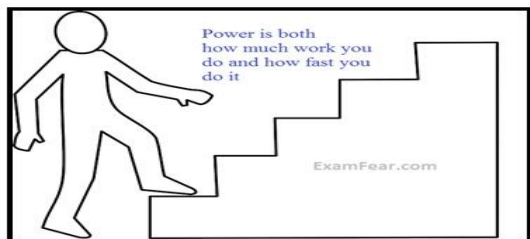
Principle of Conservation of Energy

- If the forces involved are non-conservative, part of the mechanical energy may get transformed into other forms such as heat, light and sound.
- However, the total energy of an isolated system does not change.
- Since the universe as a whole may be viewed as an isolated system, the total energy of the universe is constant.



Power

- Power is defined as the time rate at which work is done or energy is transferred.



- Average Power: Ratio of work done(W) in a total time interval of t.
 $P_{av} = W/t$
- Instantaneous Power: When the time interval ,t ,approaches zero the limiting value of average power becomes instantaneous power.
 $P = dW/dt$
- We can write $W = F.dr$,
 $P = F . dr/dt$
 $P = F.v$, where v is instantaneous velocity.
- Power is a scalar quantity
- SI unit of power – Watt(W)
- 1 hp = 746 W

Example: A pump on the ground floor of a building can pump up water to fill a tank of volume 30 m^3 in 15 min. If the tank is 40 m above the ground, and the efficiency of the pump is 30%, how much electric power is consumed by the pump?

Solution: $P = W/t = mgh/t$

mass of water to be moved = $\rho V = 30000 \text{ kg}$

$g = 9.8$

$h = 40 \text{ m}$

$t = 15 \times 60 = 900 \text{ s}$

$P = 13066.67 \text{ W} = 13.067 \text{ kW}$

Now $\eta = P/P_{\text{ACTUAL}} \Rightarrow P_{\text{ACTUAL}} = 13.067/0.3 = 43.6 \text{ kW}$

Collosion

- A collision is an event in which two or more bodies exert forces on each other for a relatively short time.

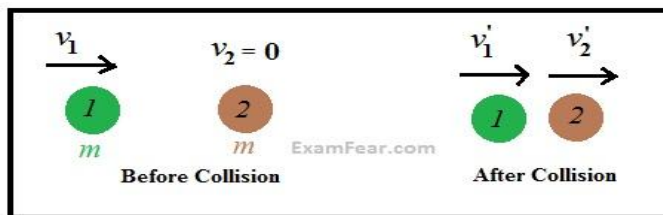


- In all collisions the total linear momentum is conserved.
- The total impulse on the first object is equal and opposite to that on the second, if two bodies collide.
- Elastic collision is when the initial Kinetic energy is equal to the final kinetic energy.
- Inelastic collision is when some of the kinetic energy is lost after collision.
- Completely inelastic collision is when the bodies after collision move together .

Collision in 1-D

- If the initial velocities and final velocities of both the bodies are along the same straight line, then it is called a one-dimensional collision, or head-on collision.

Elastic collision:



(A ball of mass m_1 with initial velocity v_1 strikes a ball of mass m_2 initially at rest and after collision ball 1 moves with velocity v_1' and ball 2 moves with velocity v_2' , in the same direction)

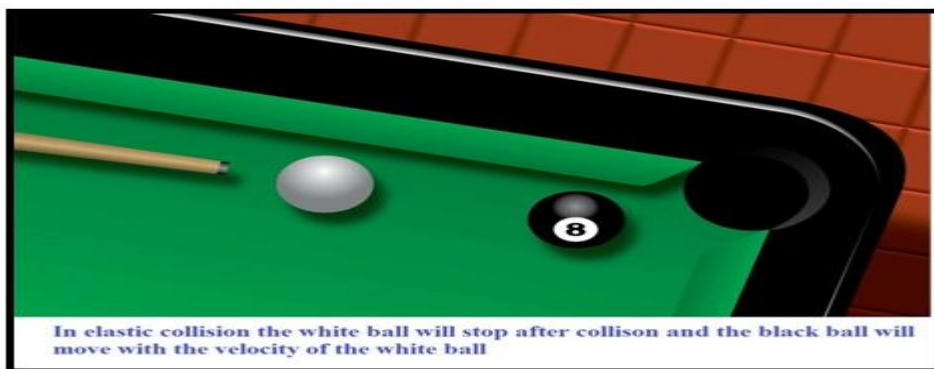
- Momentum conservation: $m_1 v_1 + m_2 v_2 = m_1 v_1' + m_2 v_2'$
- KE conservation: $m_1 v_1^2 + m_2 v_2^2 = m_1 v_1'^2 + m_2 v_2'^2$
- Where m_1, m_2 are the masses of the two blocks
 v_1 is initial velocity of block 1, $v_2=0$ here
 v_1' is final velocity of block 1
- After solving these two equations we get,

$$v_1' = \frac{m_1 - m_2}{m_1 + m_2} v_1$$

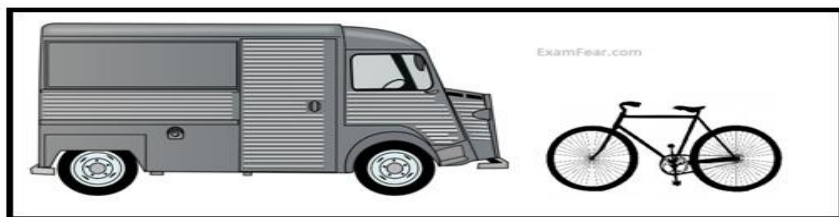
$$v_2' = \frac{2 m_1}{m_1 + m_2} v_1$$

Special cases in elastic collision :

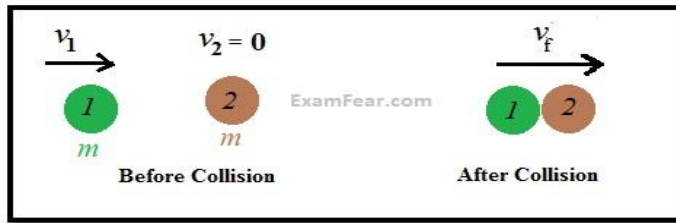
- Case 1 – If the two masses are equal $m_1=m_2$, then, $v_1' = 0$ & $v_2' = v_1$
The first mass comes to rest and pushes off the second mass with its initial speed on collision.



- Case 2 – If $m_2 \gg m_1$ then, $v_1' \approx -v_1$ & $v_2' \approx 0$
The heavier mass is undisturbed while the lighter mass reverses its velocity



Completely inelastic collision



(A ball of mass m_1 with initial velocity v_1 strikes a ball of mass m_2 initially at rest and the two ball stick to each other after collision, in the same direction)

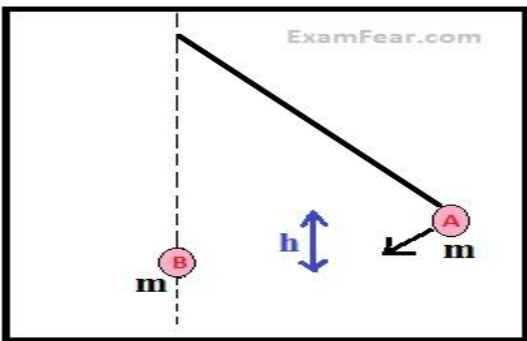
Momentum conservation: $m_1 v_1 + m_2 v_2 = (m_1 + m_2) v_f$

$$v_f = \frac{m_1}{m_1 + m_2} v_1$$

KE conservation: $m_1 v_1^2 + m_2 v_2^2 = (m_1 + m_2) v_f^2$

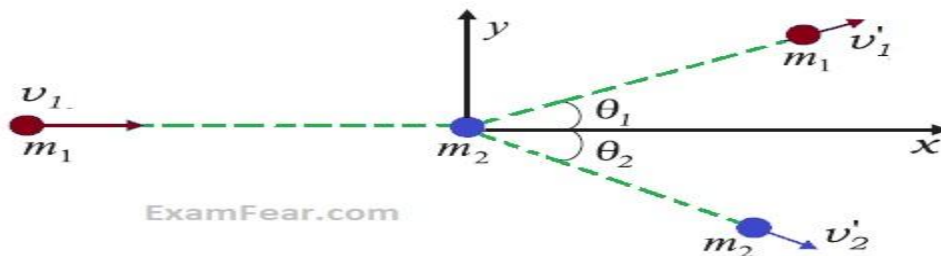
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- Where m_1, m_2 are the masses of the two blocks
 v_1 is initial velocity of block 1, $v_2=0$ here
 v_f is final velocity of the two block moving together

Example: The bob A of a pendulum is released to hit vertically another bob B of the same mass at rest on a table as shown in Figure. How high does the bob A rise after the elastic collision?



Solution: Since this is a case of both objects with same mass, so the bob B will move with the velocity of bob A. Now with energy conservation it will rise to a height of h only.

Collosions in 2-D



(A ball of mass m_1 with initial velocity v_1 strikes a ball of mass m_2 initially at rest after collision, ball 1 moves with velocity v'_1 and ball 2 moves with velocity v'_2 with directions as shown in figure)

➤ Momentum conservation :

$$\text{x-axis : } m_1 v_1 = m_1 v'_1 \cos \theta_1 + m_2 v'_2 \cos \theta_2$$

$$\text{y-axis : } 0 = m_1 v'_1 \sin \theta_1 - m_2 v'_2 \sin \theta_2$$

➤ If collision is elastic , Kinetic Energy conservation :

$$\frac{1}{2} m_1 v_1^2 = \frac{1}{2} m_1 v'^2_1 + \frac{1}{2} m_2 v'^2_2$$

- With the above equations we have to solve the problem

Example: Two balls initially travelling along the x-axis with opposite velocities collide with each other obliquely, is it possible that they will move in the y-axis after collision?

Solution: Yes, it is possible, if the balls have same mass and travel with same speed. Initially their total momentum in x-direction was zero as their velocities were opposite; also in y-direction it is zero because they do not have velocity in that direction. Now after collision if their velocities are still equal and in opposite direction, the total momentum still remains zero.

Thank You

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